

# Selection Table of Servo Capacity

## 1. General customer information

Date	Model Name / All model	Name	called by DPA to	TEL	email address
Name of Product		The number of shaft		FAX	
Control Type	Standard Type(VS)	Speed, position, torque, speed/position, speed/torque, position/torque			
	Controller Type(VS)	Linear coordinates operation(x-y), Rotary coordinates operation(index, turret), Feeder operation, Position decision operation after sensor, 2 Step round operation(drill, automatic door), Pulse synchronized operation, PUSH-PULL operation(pressure, tensile control, press)			
	Tension Control Type	Normal type, Radius compensation control type			

## 2. Operation Cycle and Load Spec.

1. Operation cycle	2. Ball screw(horizontal axis)	3. Ball screw(vertical axis)
Position decision length $L_d$ [sec] Position decision time $t_d$ [sec] Transfer speed $V_d$ [m/min]	Operation period $t_c$ [sec] Acceleration time $t_a$ [sec] Deceleration time $t_r$ [sec]	
4. Timing belt	5. Rack pinion	6. Roll feeder
Load weight W [kg] Impellent force F [kg] Friction coefficient $\mu$ Total efficiency $\eta$ Deceleration ratio R(Nm/N t) Gear+Coupling $GD^2$ [kg · cm <sup>2</sup> ] Ball screw pitch P [mm] Ball screw diameter D [mm] Ball screw length L [mm]	Load weight W [kg] Counter weight W2 [kg] Friction coefficient $\mu$ Total efficiency $\eta$ Deceleration ratio R(Nm/N t) Gear+Coupling $GD^2$ [kg · cm <sup>2</sup> ] Ball screw pitch P [mm] Ball screw diameter D [mm] Ball screw length L [mm]	
7. Rotating body		
Load $GD^2$ [kg · cm <sup>2</sup> ] Tension F [kg] Pressure P [kg] Roll diameter D [mm] Friction coefficient $\mu$ Total efficiency $\eta$ Deceleration ratio R(Nm/N t) Gear+Coupling $GD^2$ [kg · m <sup>2</sup> ]	Load $GD^2$ [kg · cm <sup>2</sup> ] Load torque $T_d$ [kg · cm] Total efficiency $\eta$ Deceleration ratio R(Nm/N t) Gear+Coupling $GD^2$ [kg · cm <sup>2</sup> ]	